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Fig. 3

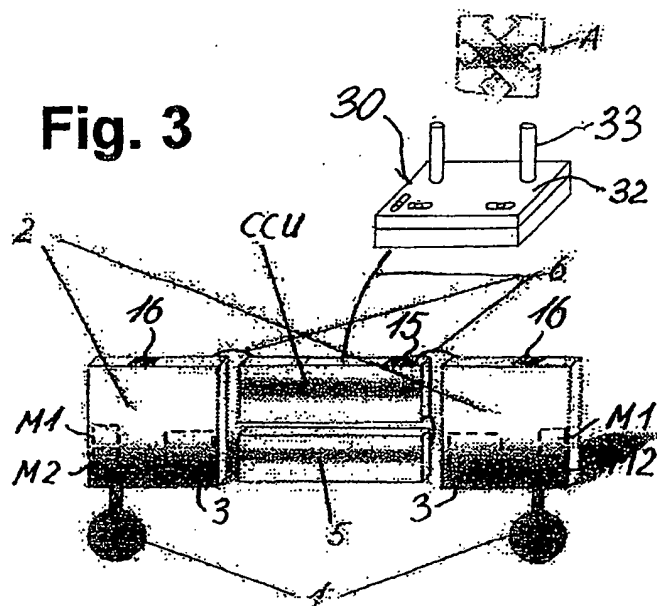
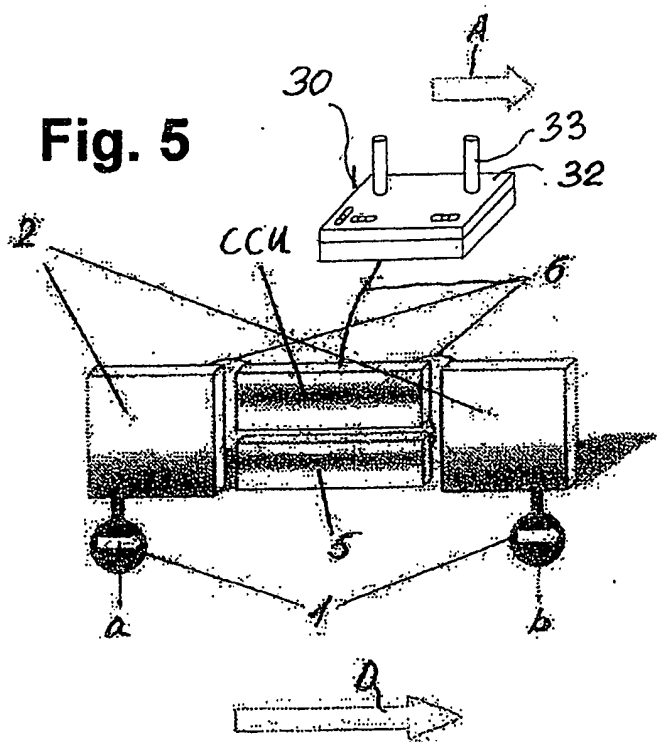


Fig. 5



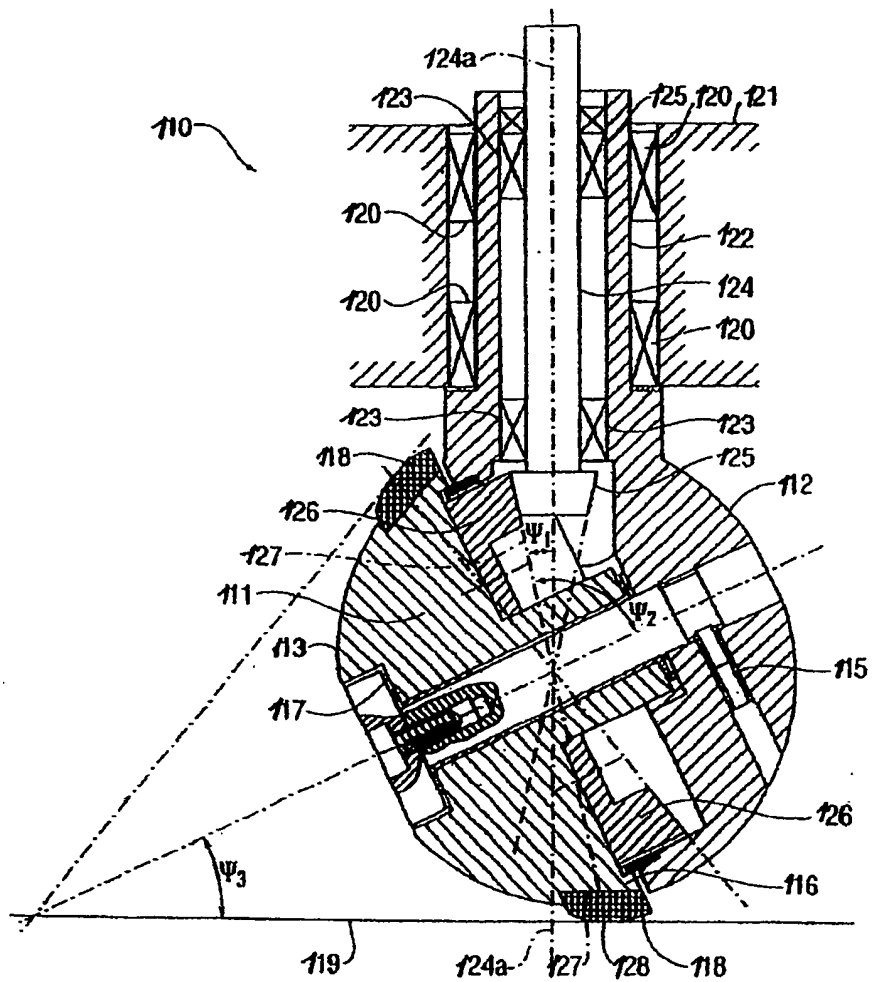


Fig. 4

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Fig. 6

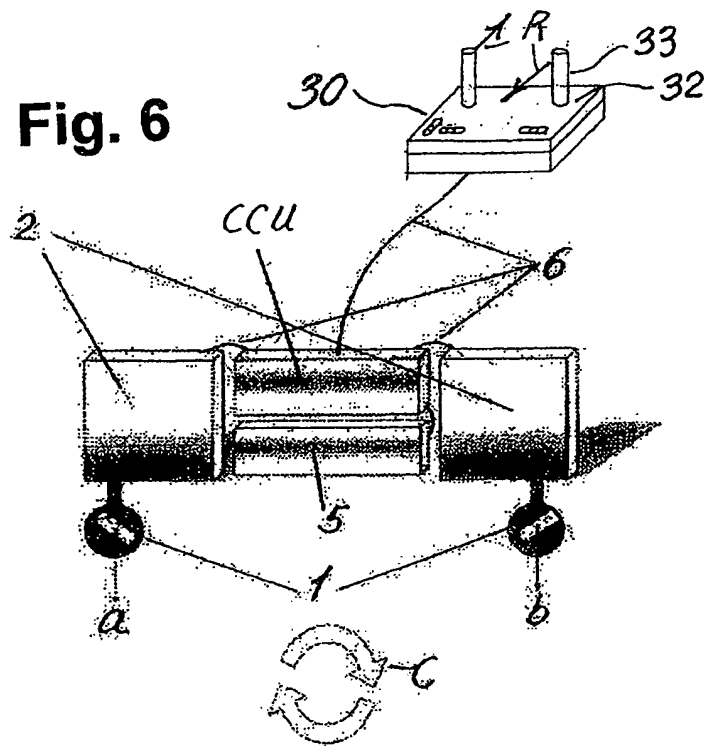
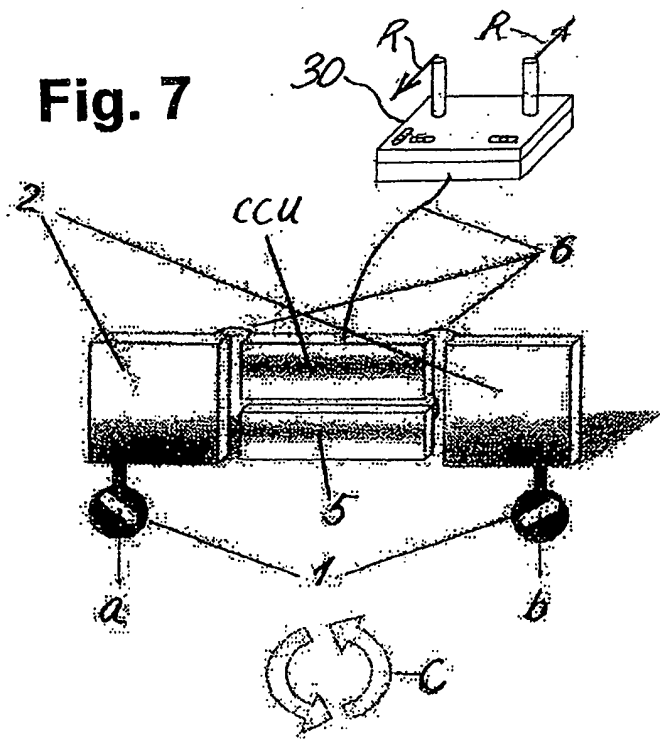


Fig. 7



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Fig. 8

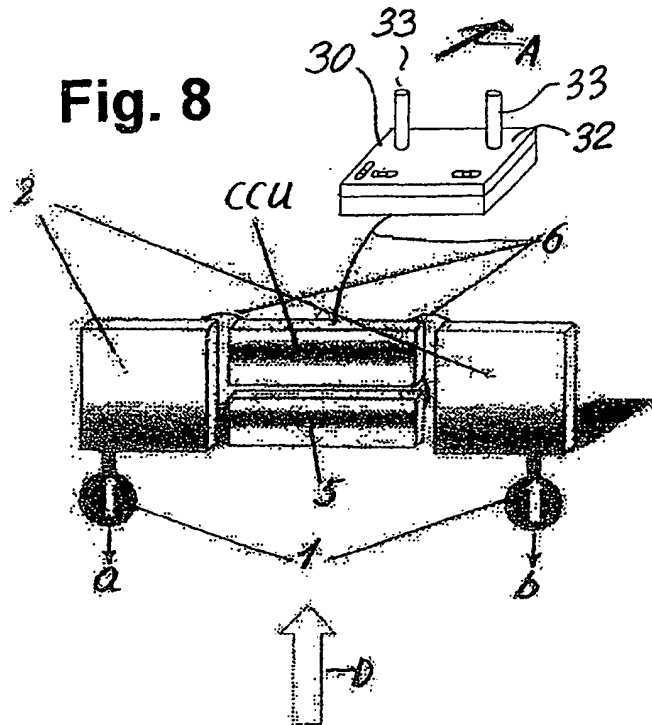
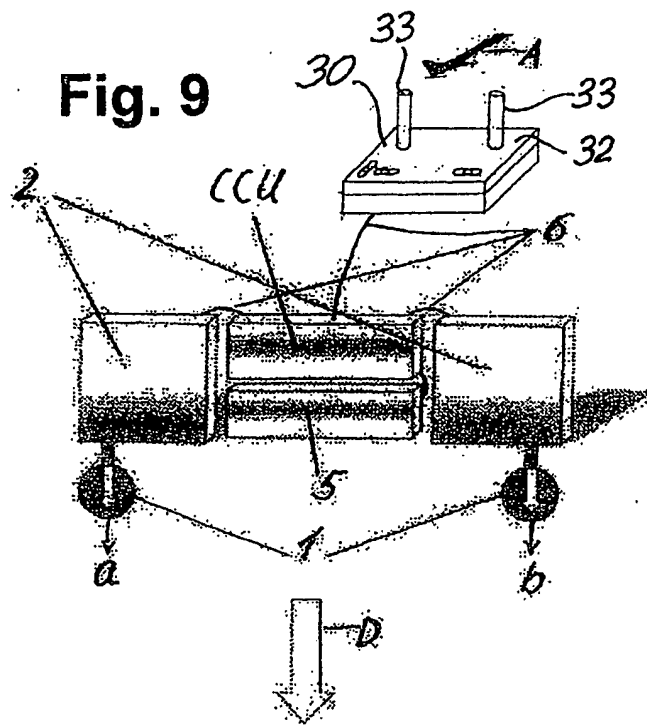


Fig. 9



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Fig. 10

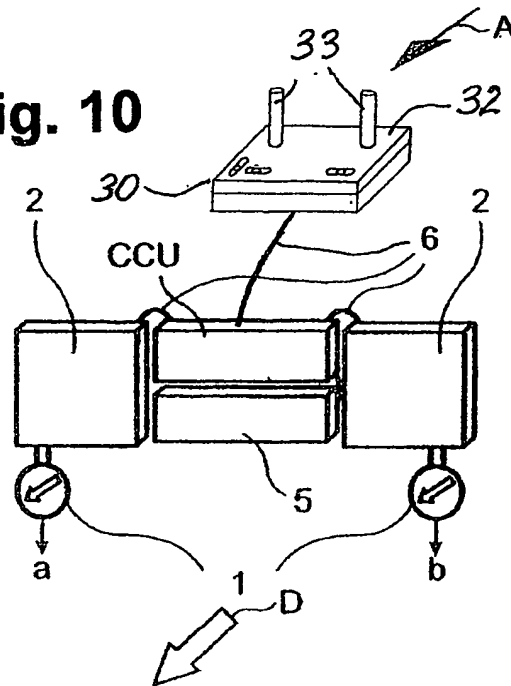
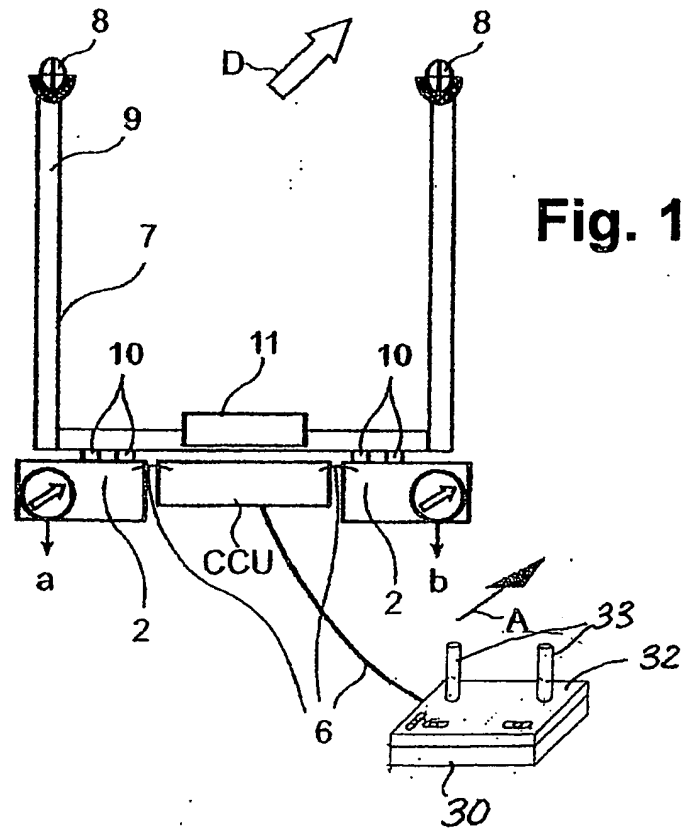


Fig. 11



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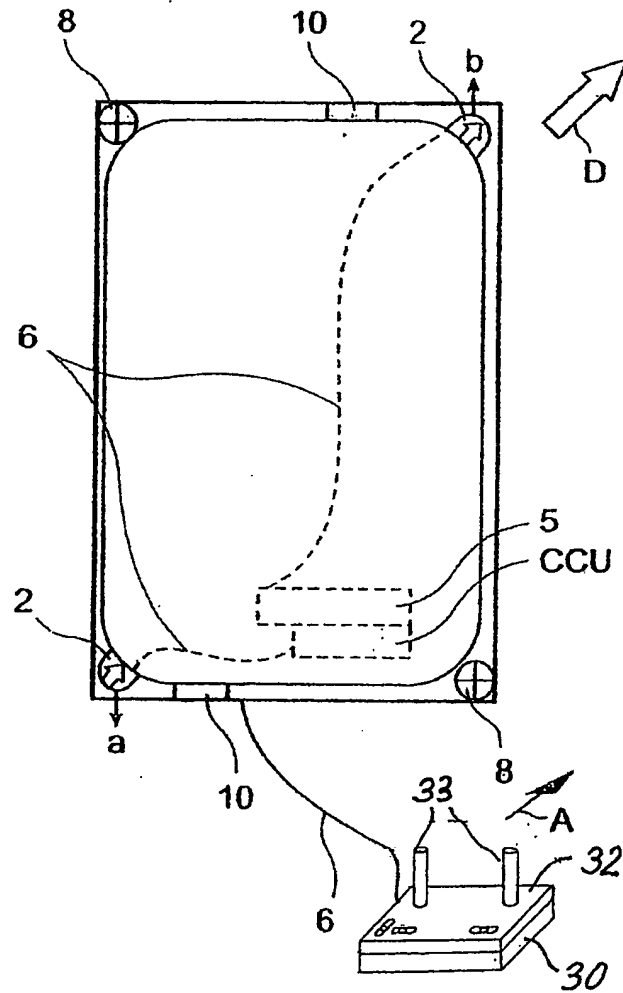
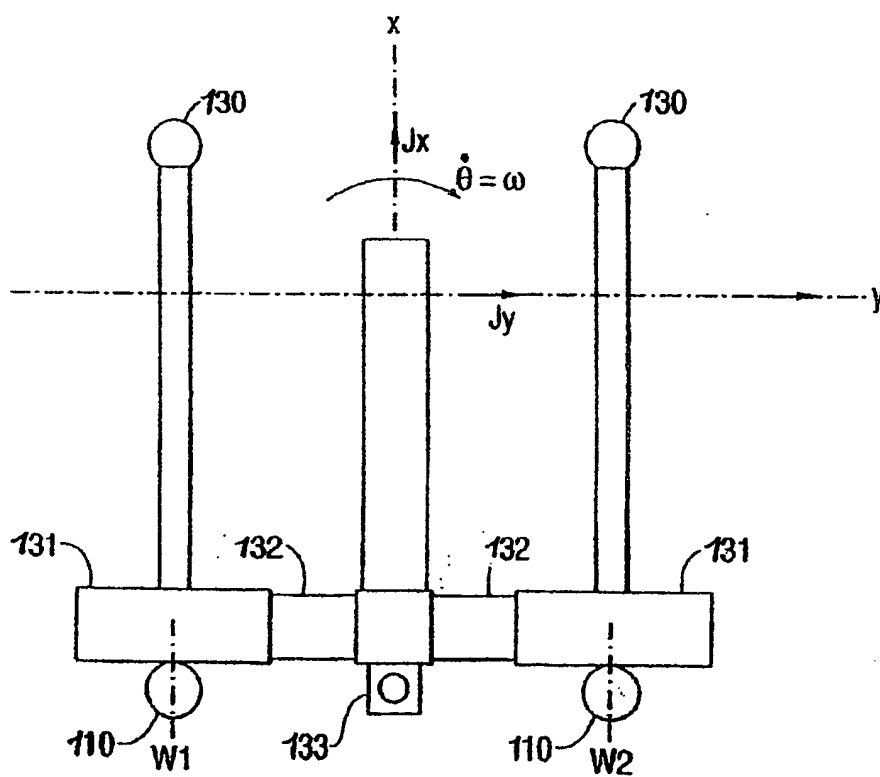
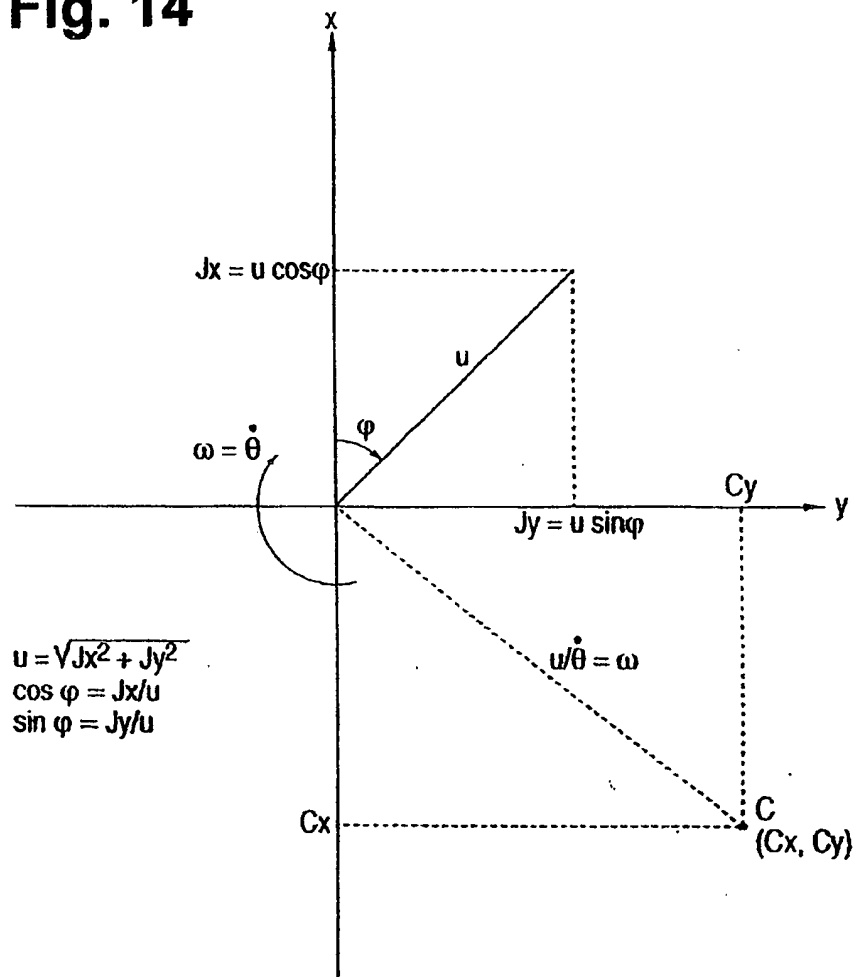


Fig. 12

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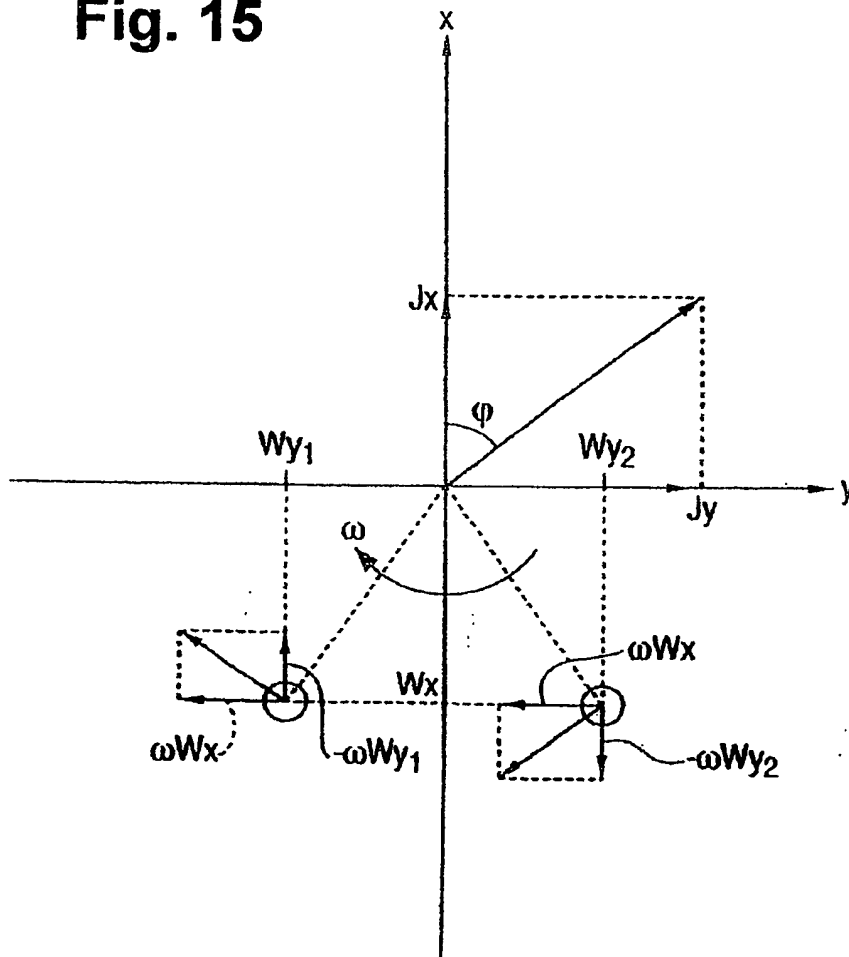
Fig. 13

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Fig. 14

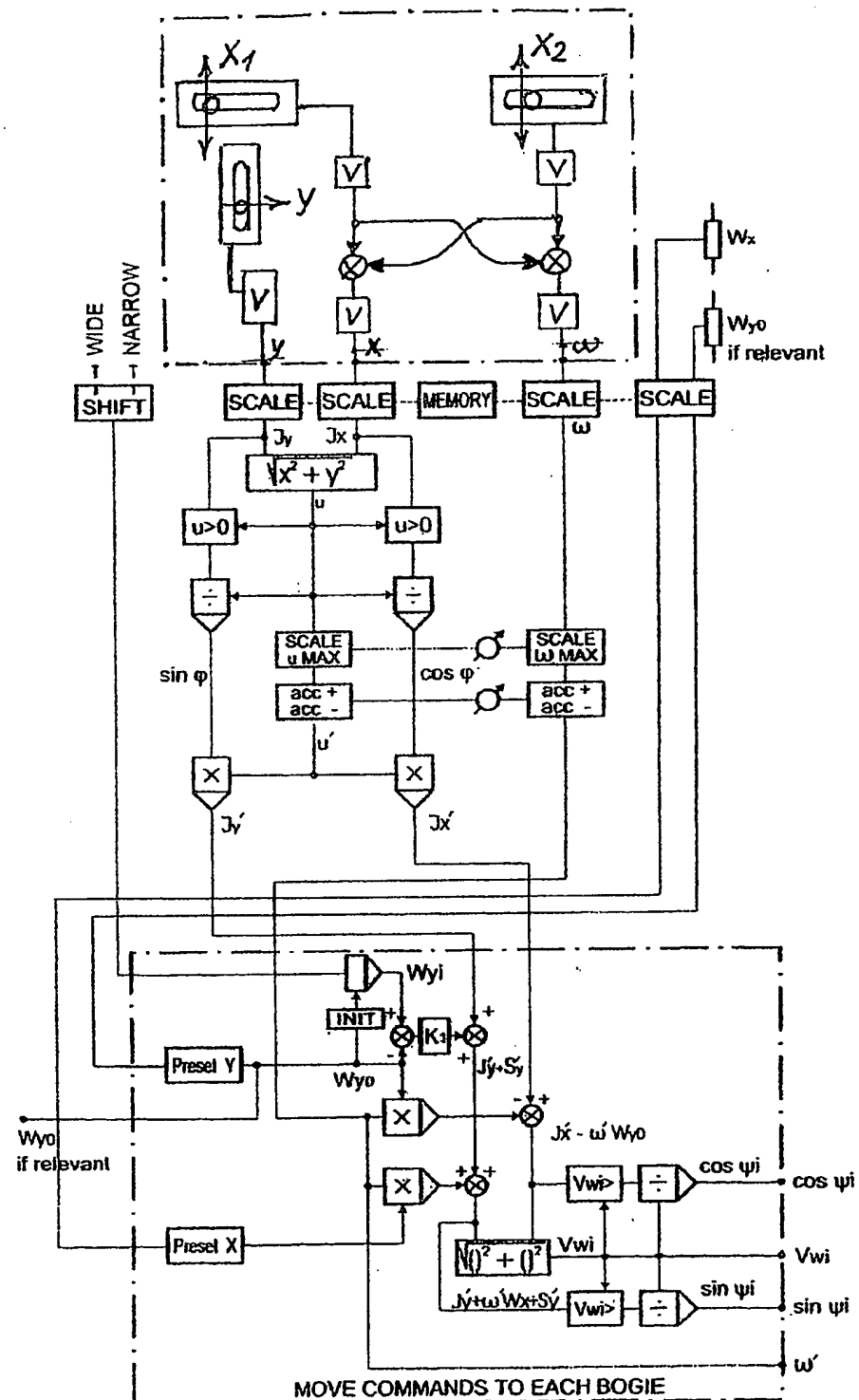
$Cx = -\frac{u}{\dot{\theta}} \sin \varphi = Jy/\dot{\theta}$ $Cy = \frac{u}{\dot{\theta}} \cos \varphi = Jx/\dot{\theta}$	$\left. \vphantom{\begin{matrix} Cx \\ Cy \end{matrix}} \right\} \text{CENTRE OF ROTATION}$
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Fig. 15

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Fig. 16



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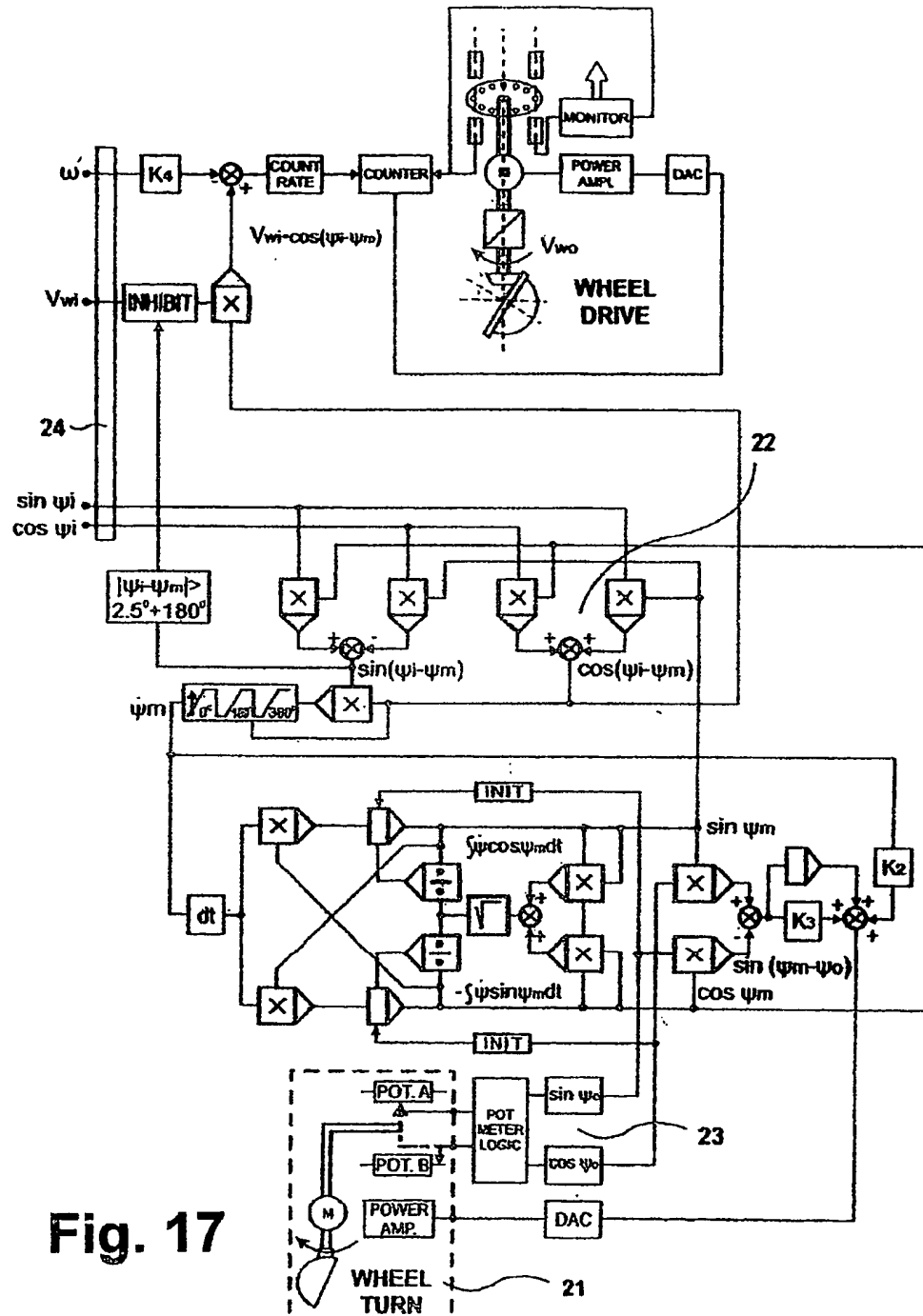


Fig. 17